



Robot Control 1988 (SYROCO'88): Selected Papers from the 2nd IFAC Symposium, Karlsruhe, FRG, 5-7 October 1988 (IFAC Symposia Series)

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Containing 88 papers, the emphasis of this volume is on the control of advanced robots. These robots may be self-contained or part of a system. The applications of such robots vary from manufacturing, assembly and material handling to space work and rescue operations. Topics presented at the Symposium included sensors and robot vision systems as well as the planning and control of robot actions. Main topics covered include the design of control systems and their implementation; advanced sensors and multisensor systems; explicit robot programming; implicit (task-orientated) robot programming; interaction between programming and control systems; simulation as a programming aid; AI techniques for advanced robot systems and autonomous robots.

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